



MEMS INERTIAL CHIP AND MODULE

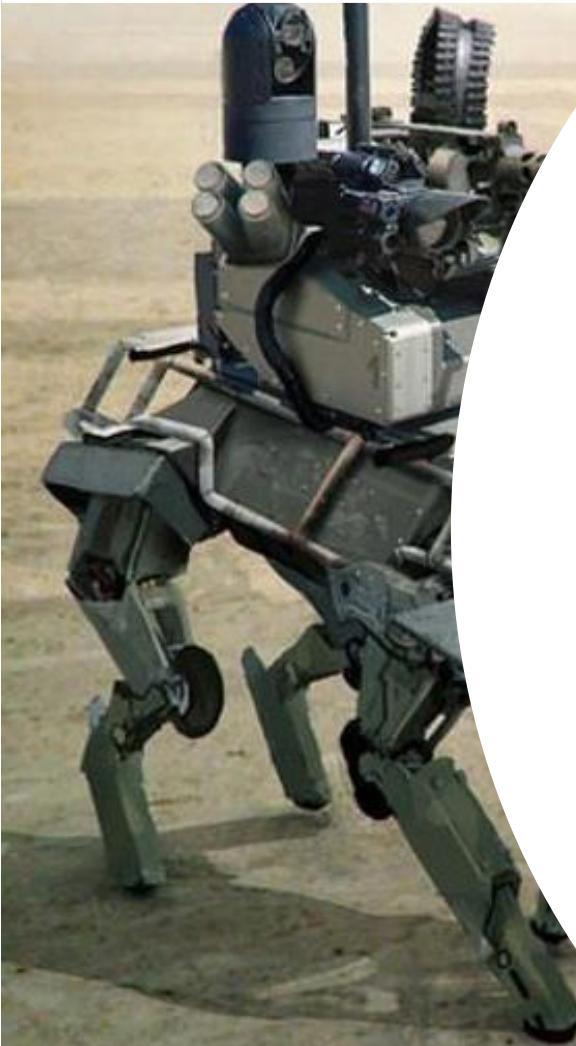


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麦新敏微
Attitude and Positioning Be Everywhere!



ACM-100/200/300 INDUSTRIAL GRADE

MEMS Accelerometer Chip and Module



| | |
|---|---------------------------------|
| Measuring Range..... | ±2/±8/±40g |
| Measuring Axis..... | X, Y, Z |
| Zero Bias Stability (10s, 1σ)..... | 1.5/7.5/22mg |
| Zero Bias Temperature Coefficient (full temperature)..... | 0.1/0.5/1.5mg/°C |
| Resolution..... | 1/5/15mg |
| Impact Resistance..... | 20000g, 2ms, 1/2 sine |
| Anti-Vibration..... | 10grms, 10~1000Hz |
| Communication Protocol..... | Rs232/Rs485/Rs422/TTL/CAN |
| Output Signal..... | Digital/Analog(current/voltage) |
| Pack and Size..... | Shell, 60*59*29mm |
| Weight..... | 180g |

ACM-1200 INDUSTRIAL GRADE

MEMS Accelerometer Chip and Module

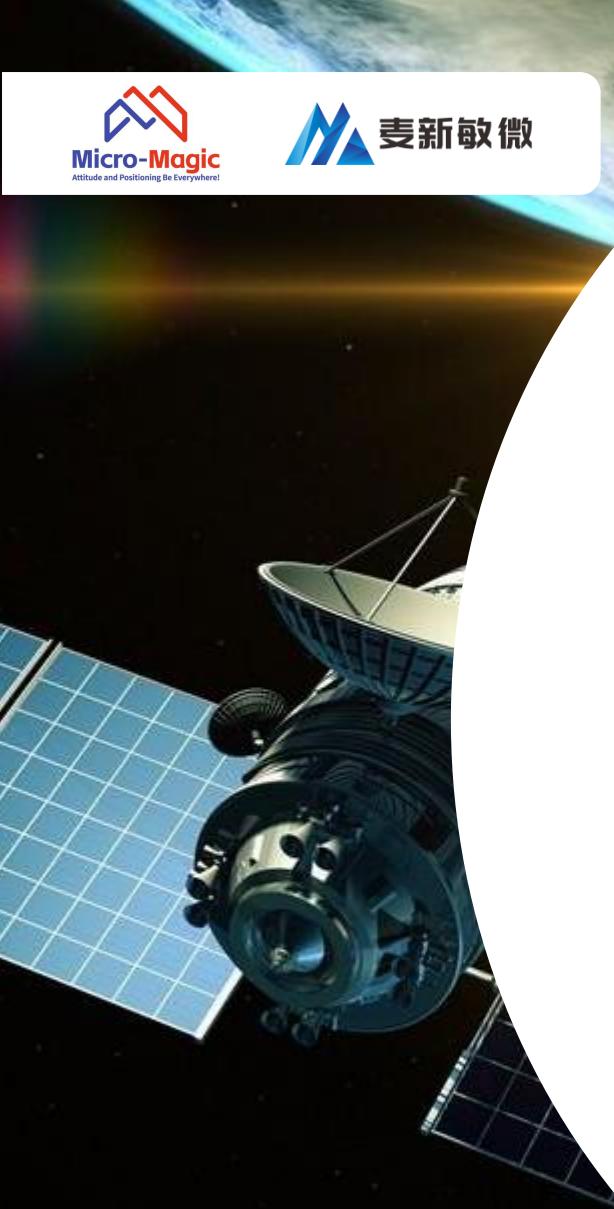


| | |
|---|---------------------------------|
| Measuring Range..... | ±10/±15/±20g |
| Measuring Axis..... | Z |
| Zero Bias Stability (10s, 1σ)..... | 100mg |
| Zero Bias Temperature Coefficient (full temperature)..... | 3mg/ $^{\circ}$ C |
| Resolution..... | 0.3/0.4/0.5mg |
| Impact Resistance..... | 20000g, 2ms, 1/2 sine |
| Anti-Vibration..... | 10grms, 10~1000Hz |
| Communication Protocol..... | I ² C/SPI/UART |
| Output Signal..... | Digital/Analog(current/voltage) |
| Pack and Size..... | Chip, 9*9*2.8mm |
| Weight..... | 1.5g |



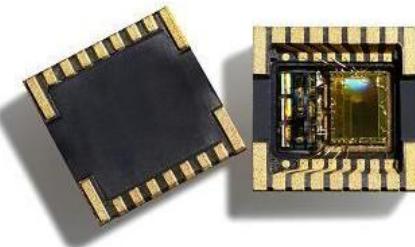


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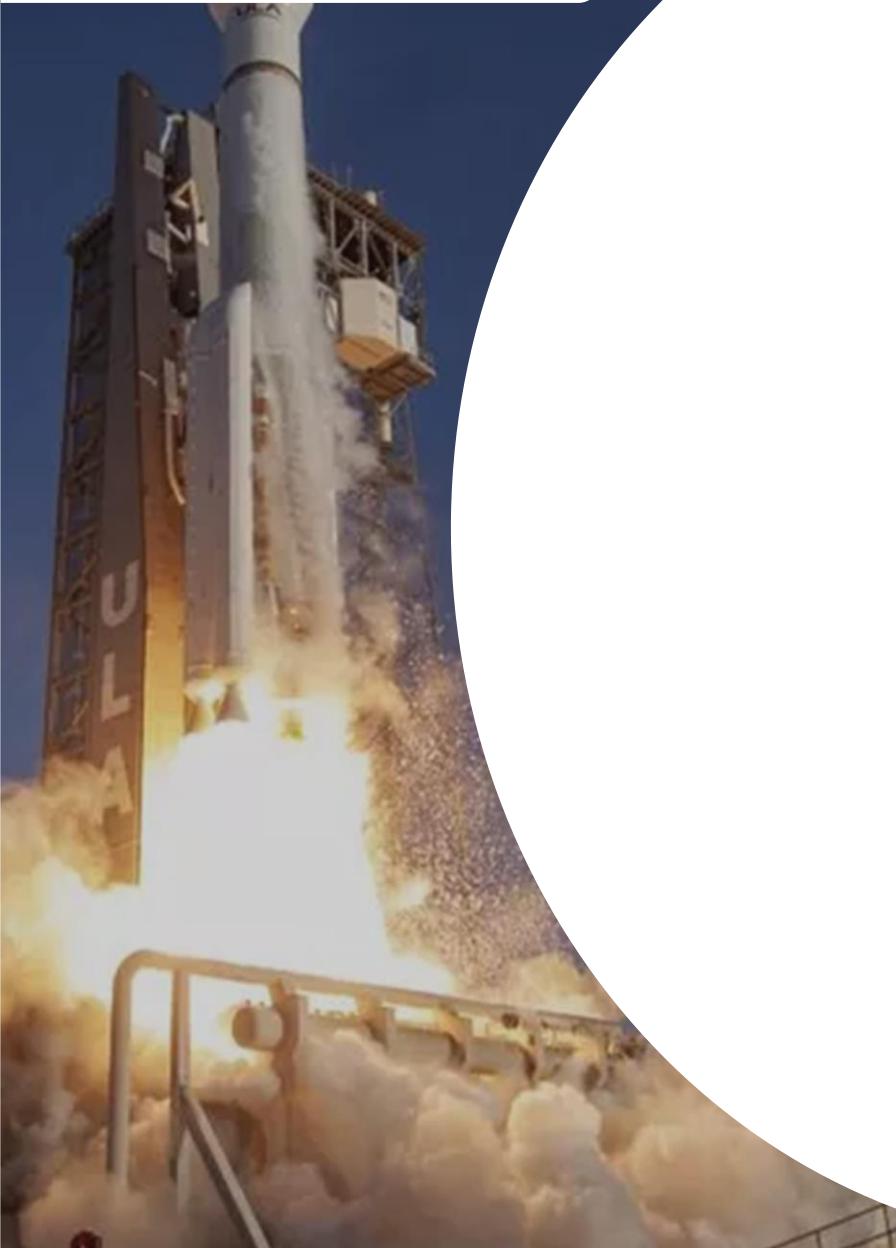


ACM-1900-A/B/C/D TACTICAL GRADE

MEMS Accelerometer Chip and Module

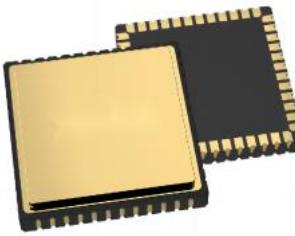


| | |
|---|--------------------------------|
| Measuring Range..... | ±2~10/±30~50/±70~100/±150~200g |
| Measuring Axis..... | X |
| Zero Bias Stability (10s, 1σ)..... | 20/50/150/250µg |
| Zero Bias Temperature Coefficient (full temperature)..... | 10/50/100/200µg/°C |
| Resolution..... | 5/10/25/50µg |
| Impact Resistance..... | 20000g, 2ms, 1/2 sine |
| Vibration Rectification Error (6grms)..... | 0.4/0.15/0.05mg |
| Communication Protocol..... | I ² C/SPI/UART |
| Output Signal..... | Digital |
| Pack and Size..... | Chip, 9*9*2.8mm |
| Weight..... | 1.5g |



MG-101/102

TACTICAL GRADE

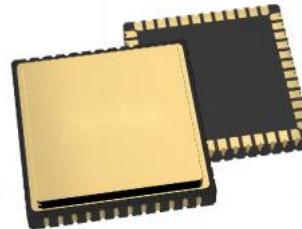


MEMS Gyroscope Chip and Module

| | |
|--|---------------------------|
| Dynamic Range..... | ±100°/s |
| Measuring Axis..... | X or Y |
| Zero Bias Stability (10s, 1σ)..... | 0.1°/hr |
| Zero Bias Repeatability (1σ)..... | 0.1°/hr |
| Random Walk Coefficient | 0.005°/√h |
| The Scale Factor of Nonlinearity..... | 200ppm (1σ) |
| The Scale Factor of Repeatability..... | 50ppm (1σ) |
| The Scale Factor of Temperature..... | 300ppm (1σ) |
| Resolution..... | 24bits |
| Impact Resistance..... | 10000g, 10ms, 1/2 sine |
| Vibration Conditions..... | 18grms, 20~2000Hz |
| Communication Protocol..... | I ² C/SPI/UART |
| Output Signal..... | Digital |
| Pack and Size..... | Chip, 11*11*0.3mm |
| Weight..... | 1.5g |

MG-401/402/403 TACTICAL GRADE

MEMS Gyroscope Chip and Module

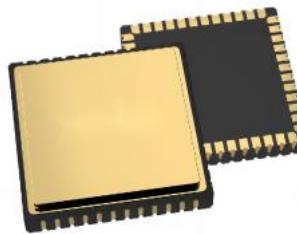


| | |
|--|--------------------------------|
| Dynamic Range..... |±400°/s |
| Measuring Axis..... |X or Y |
| Zero Bias Stability (10s, 1σ)..... |1/1/0.5°/hr |
| Zero Bias Repeatability (1σ)..... |1/0.3/0.3°/hr |
| Random Walk Coefficient |0.05/0.05/0.025°/√h |
| The Scale Factor of Nonlinearity..... |200/300/100ppm (1σ) |
| The Scale Factor of Repeatability..... |100/50/50ppm (1σ) |
| The Scale Factor of Temperature..... |500/300/100ppm (1σ) |
| Resolution..... |24bits |
| Impact Resistance..... |10000g, 10ms, 1/2 sine |
| Vibration Conditions..... |18grms, 20~2000Hz |
| Communication Protocol..... |I ² C/SPI/UART |
| Output Signal..... |Digital |
| Pack and Size..... |Chip, 11*11*0.3mm |
| Weight..... |1.5g |





MG-501/502/503 TACTICAL GRADE

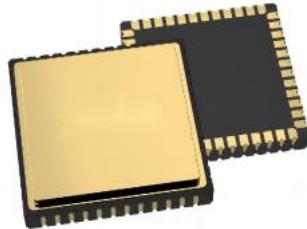


MEMS Gyroscope Chip and Module

| | |
|--|---------------------------|
| Dynamic Range..... | ±500°/s |
| Measuring Axis..... | X or Y |
| Zero Bias Stability (10s, 1σ)..... | 2.5/5/2°/hr |
| Zero Bias Repeatability (1σ)..... | 3/5/1°/hr |
| Random Walk Coefficient | 0.125/0.25/0.1°/√h |
| The Scale Factor of Nonlinearity..... | 150ppm (1σ) |
| The Scale Factor of Repeatability..... | 10/10/20ppm (1σ) |
| The Scale Factor of Temperature..... | 50ppm (1σ) |
| Resolution..... | 24bits |
| Impact Resistance..... | 10000g, 10ms, 1/2 sine |
| Vibration Conditions..... | 18grms, 20~2000Hz |
| Communication Protocol..... | I ² C/SPI/UART |
| Output Signal..... | Digital |
| Pack and Size..... | Chip, 11*11*0.3mm |
| Weight..... | 1.5g |

MG-1001/1002 INDUSTRIAL GRADE

Electronic Compass Sensor



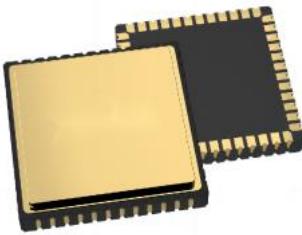
| | |
|--|---------------------------|
| Dynamic Range..... | ±1000°/s |
| Measuring Axis..... | X or Y |
| Zero Bias Stability (10s, 1σ)..... | 4/1°/hr |
| Zero Bias Repeatability (1σ)..... | 4/0.5°/hr |
| Random Walk Coefficient | 0.15/0.05°/√h |
| The Scale Factor of Nonlinearity..... | 150/100ppm (1σ) |
| The Scale Factor of Repeatability..... | 5/20ppm (1σ) |
| The Scale Factor of Temperature..... | 50/100ppm (1σ) |
| Resolution..... | 24bits |
| Impact Resistance..... | 10000g, 10ms, 1/2 sine |
| Vibration Conditions..... | 18grms, 20~2000Hz |
| Communication Protocol..... | I ² C/SPI/UART |
| Output Signal..... | Digital |
| Pack and Size..... | Chip, 11*11*0.3mm |
| Weight..... | 1.5g |



MG-2001

TACTICAL GRADE

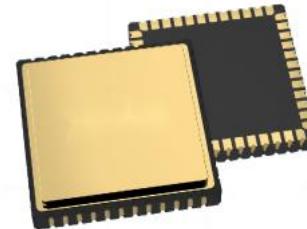
MEMS Gyroscope Chip and Module



| | |
|--|---------------------------|
| Dynamic Range..... | ±2000°/s |
| Measuring Axis..... | X or Y |
| Zero Bias Stability (10s, 1σ)..... | 5°/hr |
| Zero Bias Repeatability (1σ)..... | 5°/hr |
| Random Walk Coefficient | 0.25°/√h |
| The Scale Factor of Nonlinearity..... | 150ppm (1σ) |
| The Scale Factor of Repeatability..... | 5ppm (1σ) |
| The Scale Factor of Temperature..... | 50ppm (1σ) |
| Resolution..... | 24bits |
| Impact Resistance..... | 10000g, 10ms, 1/2 sine |
| Vibration Conditions..... | 18grms, 20~2000Hz |
| Communication Protocol..... | I ² C/SPI/UART |
| Output Signal..... | Digital |
| Pack and Size..... | Chip, 11*11*0.3mm |
| Weight..... | 1.5g |

MG-4001/4002 TACTICAL GRADE

MEMS Gyroscope Chip and Module



| | |
|--|-----------------------------|
| Dynamic Range..... | $\pm 4000^{\circ}/s$ |
| Measuring Axis..... | X or Y |
| Zero Bias Stability (10s, 1σ)..... | $10/4^{\circ}/hr$ |
| Zero Bias Repeatability (1σ)..... | $5/1^{\circ}/hr$ |
| Random Walk Coefficient | $0.5/0.15^{\circ}/\sqrt{h}$ |
| The Scale Factor of Nonlinearity..... | 100ppm (1σ) |
| The Scale Factor of Repeatability..... | 10ppm (1σ) |
| The Scale Factor of Temperature..... | 100ppm (1σ) |
| Resolution..... | 24bits |
| Impact Resistance..... | 10000g, 10ms, 1/2 sine |
| Vibration Conditions..... | 18grms, 20~2000Hz |
| Communication Protocol..... | I ² C/SPI/UART |
| Output Signal..... | Digital |
| Pack and Size..... | Chip, 11*11*0.3mm |
| Weight..... | 1.5g |





The Leader in China Inertial Sensor Market



Unmanned Aerial
Vehicles



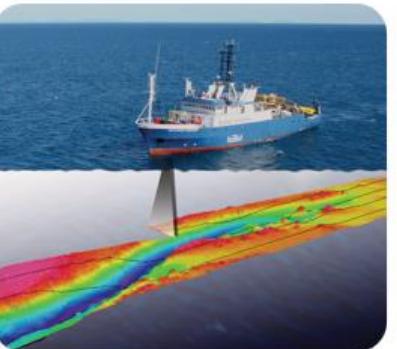
Satellites



Autonomous Vehicles



Remotely Operated
Underwater Vehicles



Maritime Echosounder
Application



Petroleum Extraction
and Exploration